

Uncertainty of indirect measurements

Error propagation

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Indirect measurements

- Let us suppose, the expected value and standard deviation of the random variable X were estimated based on measurements.
- What can we say about the parameters of a random variable $Y=f(X)$?

Example: We measure the diameter d of a bearing ball. Based on the diameter, the volume of the ball is:

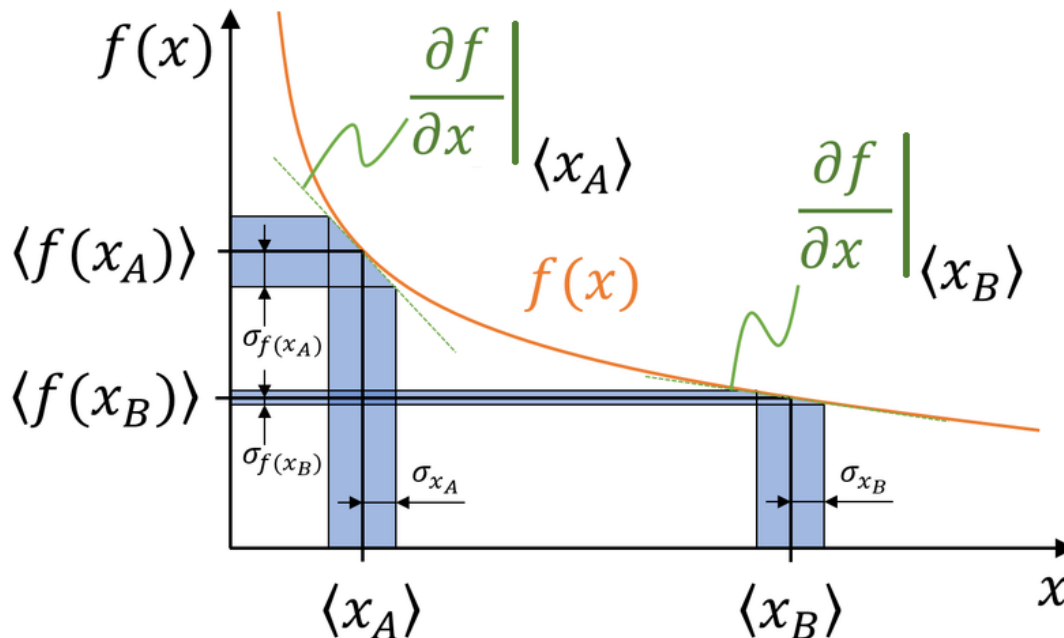
$$V = \frac{4}{3} \pi r^3 = \frac{1}{6} \pi d^3$$

If the expected value and standard deviation of the diameter are known, what can we say about the expected value and standard deviation of the volume?

If $f(x)$ is a strictly monotonic function in the proximity of the directly measured value, and the standard deviation of the directly measured value is "small", then a "good" approximation of $f(x)$ is its linearized Taylor series:

$$\mu(f(x)) = f(\mu(x))$$

$$\sigma(f(x)) = \left. \frac{\partial f}{\partial x} \right|_{\mu(x)} \cdot \sigma(x)$$



Indirect measurements

- Let's assume that the expected values and standard deviations of the independent random variables $X_1 \dots X_N$ were estimated based on measurements.
- What can we say about the parameters of a random variable $Y=f(X_1 \dots X_N)$?

Example: We measure the diameter d and mass m of a bearing ball. Based on the diameter and mass, the density of the ball is:

$$\rho = \frac{m}{V} = \frac{6m}{\pi d^3}$$

If the expected values and standard deviations of diameter and mass are known, what can we say about the expected value and standard deviation of density?

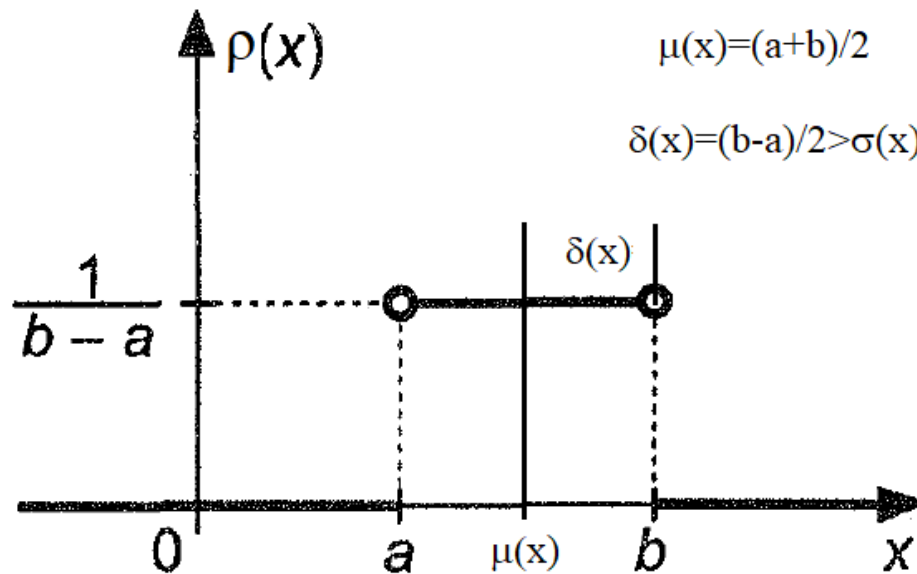
Error propagation law by Gauss

$$\sigma(f(x_1 \dots x_N)) = \sqrt{\sum_{i=1}^N \left(\frac{\partial f}{\partial x_i} \right)_{x_i = \mu(x_i)}^2 \cdot \sigma^2(x_i)}$$

Note: The condition for the applicability of the above error propagation law is, that the values of all partial derivatives involved in it are different from zero.

A special case of the continuous uniform distribution - the concept of error limits

- In the case of measurements by the scale, the density function of the random error is:



$\delta(x)$ – absolute limit or absolute error

$$\delta(x) = \frac{b-a}{2} > \sigma(x) = \frac{b-a}{\sqrt{12}}$$

The absolute error is always an overestimate of the standard deviation!

Error propagation law of measurements with absolute error

$$\delta(f(x_1 \dots x_N)) = \sum_{i=1}^N \left| \frac{\partial f}{\partial x_i} \right|_{x_i = \mu(x_i)} \cdot \delta(x_i)$$

Note: The condition for the applicability of the above error propagation law is, that the values of all partial derivatives included in it are different from zero.