



Vektoranalízis dióhéjban

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Operátorok

- matematikai műveletek függvényeken

Pé.: - koordinátával való szorzás művelete: $x \cdot$ ($x \cdot f(x) = g(x)$)

- ha $f(x) = x^2 \Rightarrow x \cdot f(x) = g(x) = x \cdot x^2 = x^3$

- ha $f(x) = \sin x \Rightarrow x \cdot f(x) = g(x) = x \cdot \sin x$

- koordináta szerinti deriválás művelete: x'

- ha $f(x) = x^2 \Rightarrow (x^2)' = g(x) = 2x$

- ha $f(x) = \sin x \Rightarrow (\sin x)' = g(x) = \cos x$

Vektorfüggvények: $f(\vec{r}) = f(x, y, z)$ - skálár; $\vec{V}(\vec{r})$ - vektor

Nabla - operátor: $\vec{\nabla} \equiv \left(\frac{\partial}{\partial x} ; \frac{\partial}{\partial y} ; \frac{\partial}{\partial z} \right)$

Gradiens: $\vec{\nabla} f(x, y, z) \equiv \left(\frac{\partial f}{\partial x} ; \frac{\partial f}{\partial y} ; \frac{\partial f}{\partial z} \right)$ - vektor

Divergencia: $\vec{\nabla} \cdot \vec{V}(x, y, z) \equiv \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$ - skálár

Rotáció: $\vec{\nabla} \times \vec{V} \equiv \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix} \equiv \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} ; - \left(\frac{\partial v_z}{\partial x} - \frac{\partial v_x}{\partial z} \right) ; \frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right)$
- vektor

Pelda:

$$f = x^2 + 2y + \frac{3}{z} \quad - \text{skalár függvény}$$

$$\vec{\nabla} f = \frac{\partial f}{\partial x} \vec{i} + \frac{\partial f}{\partial y} \vec{j} + \frac{\partial f}{\partial z} \vec{k} = 2x \cdot \vec{i} + 2 \vec{j} - 3 \cdot \frac{1}{z^2} \cdot \vec{k} \quad - \text{vektor-vektor függvény}$$

Pelda:

$$f_x = x^2 + 2y + 3 \sin z$$

$$f_y = 3x - \frac{4}{y} + 5z^2$$

$$f_z = 4 \sin x + 3 e^y - 4z$$

vektor-vektor függvény

$$\vec{\nabla} \cdot \vec{f} = \operatorname{div} \vec{f} = \frac{\partial f_x}{\partial x} + \frac{\partial f_y}{\partial y} + \frac{\partial f_z}{\partial z} = 2x + \frac{4}{y^2} - 4 \quad - \text{skalár függvény}$$

$$\vec{\nabla} \times \vec{f} = \operatorname{rot} \vec{f} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f_x & f_y & f_z \end{vmatrix} = \vec{i} \begin{vmatrix} \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f_y & f_z \end{vmatrix} - \vec{j} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ f_x & f_z \end{vmatrix} + \vec{k} \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ f_x & f_y \end{vmatrix} = \vec{i} \left(\frac{\partial f_z}{\partial y} - \frac{\partial f_y}{\partial z} \right) - \vec{j} \left(\frac{\partial f_z}{\partial x} - \frac{\partial f_x}{\partial z} \right) + \vec{k} \left(\frac{\partial f_y}{\partial x} - \frac{\partial f_x}{\partial y} \right) =$$

$$= \vec{i} (3 e^y - 10z) - \vec{j} (-4 \sin x - 3 \cos z) + \vec{k} (3 - 2) = (3 e^y - 10z) \vec{i} + \vec{j} (4 \sin x + 3 \cos z) + \vec{k}$$

vektor-vektor függvény

Gauss - Osztrogradskij tétel

$$\oint_A \vec{v} \cdot d\vec{A} = \int_V \operatorname{div} \vec{v} dV$$



Stokes - tétel

$$\oint_S \vec{v} \cdot d\vec{s} = \int_A \operatorname{rot} \vec{v} \cdot d\vec{A}$$

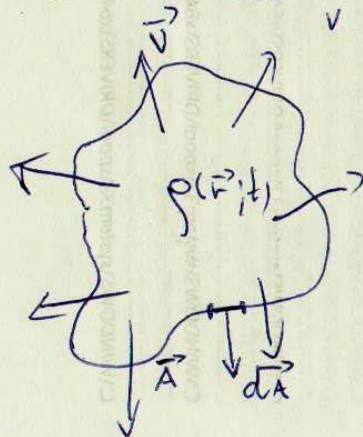


Tömegmegmaradás - tételle

$\rho(\vec{r}; t)$ - tömegsűrűség

$m(t) = \int_V \rho(\vec{r}; t) dV$ - a tömeg a V térfogaton belül a t időpillanatban

$$-\frac{dm}{dt} = -\frac{d}{dt} \int_V \rho(\vec{r}; t) dV = -\int_V \frac{\partial \rho(\vec{r}; t)}{\partial t} dV = \int_A \rho(\vec{r}; t) \cdot \vec{v}(\vec{r}; t) \cdot d\vec{A} \stackrel{\text{G-O}}{=} \int_V \operatorname{div}(\underbrace{\rho \cdot \vec{v}}_{\vec{j}(\vec{r}; t) \text{ - tömegáram sűrűség}}) dV$$



$$\int_V \frac{\partial \rho}{\partial t} dV + \int_V \operatorname{div} \vec{j} dV = 0 \quad \forall V\text{-re}$$

$$\int_V \left(\frac{\partial \rho}{\partial t} + \operatorname{div} \vec{j} \right) dV = 0 \quad \forall V\text{-re}$$

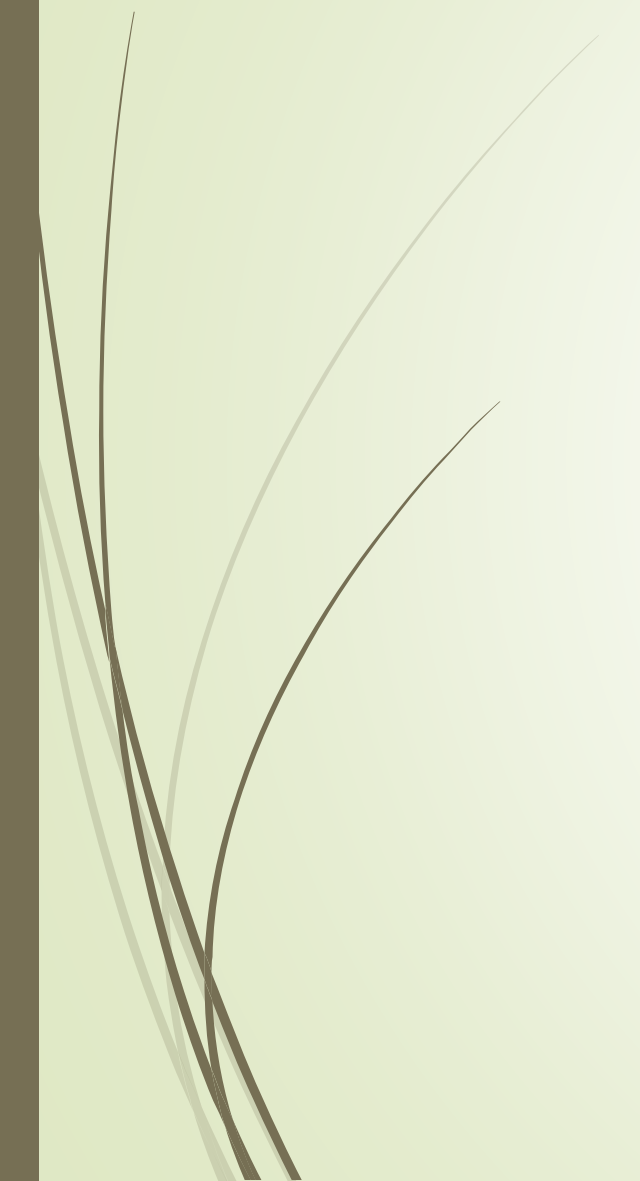
$$\left| \frac{\partial \rho}{\partial t} + \operatorname{div} \vec{j} = 0 \right| - \text{kontinuitási egyenlet}$$

$$\operatorname{div}(\operatorname{grad} f) = \Delta f$$

Bizonyítás:

$$\vec{u} = \operatorname{grad} f = \left(\frac{\partial f}{\partial x} ; \frac{\partial f}{\partial y} ; \frac{\partial f}{\partial z} \right) = (u_x ; u_y ; u_z)$$

$$\begin{aligned} \operatorname{div} \vec{u} &= \vec{\nabla} \cdot \vec{u} = \frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right) + \frac{\partial}{\partial z} \left(\frac{\partial f}{\partial z} \right) = \\ &= \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} = \Delta f \end{aligned}$$



ITT A VÉGE, FUSS EL VÉLE ...